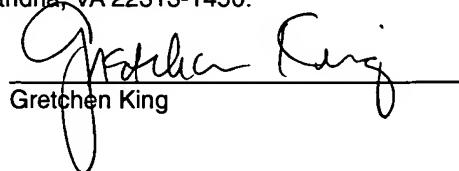


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Gretchen King

APPLICATION FOR UNITED STATES PATENT

FOR

**SUBSEA CHEMICAL INJECTION UNIT FOR ADDITIVE INJECTION AND
MONITORING SYSTEM FOR OILFIELD OPERATIONS**

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CROSS-REFERENCE TO RELATED APPLICATIONS

This application takes priority from U.S. Provisional Application serial number 60/403,445 filed August 14, 2002.

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BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates generally to oilfield operations and more particularly to a subsea chemical injection and fluid processing systems and methods.

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2. Background of the Art

Conventional offshore production facilities often have a floating or fixed platforms stationed at the water's surface and subsea equipment such as a well head positioned over the subsea wells at the mud line of a seabed. The 15 production wells drilled in a subsea formation typically produce fluids (which can include one or more of oil, gas and water) to the subsea well head. This fluid (wellbore fluid) is carried to the platform via a riser or to a subsea fluid separation unit for processing. Often, a variety of chemicals (also referred to herein as "additives") are introduced into these production wells and processing units to 20 control, among other things, corrosion, scale, paraffin, emulsion, hydrates, hydrogen sulfide, asphaltenes, inorganics and formation of other harmful chemicals. In offshore oilfields, a single offshore platform (e.g., vessel, semi-submersible or fixed system) can be used to supply these additives to several producing wells.

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The equipment used to inject additives includes at the surface a chemical supply unit, a chemical injection unit, and a capillary or tubing (also referred to herein as "conductor line") that runs from the offshore platform through or along the riser and into the subsea wellbore. Preferably, the additive injection systems supply precise amounts of additives. It is also desirable for these systems to 30 periodically or continuously monitor the actual amount of the additives being dispensed, determine the impact of the dispersed additives, and vary the amount of dispersed additives as needed to maintain certain desired parameters of interest within their respective desired ranges or at their desired values.

In conventional arrangements, however, the chemical injection unit is positioned at the water surface (e.g., on the offshore platform or a vessel), which can be several hundred to thousands of feet) from the subsea wellhead. Moreover, the tubing may direct the additives to produced fluids in the wellbores

5 located hundreds or thousands of feet below the seabed floor. The distance separating the chemical injection unit and the locus of injection activity can reduce the effectiveness of the additive injection process. For example, it is known that the wellbore is a dynamic environment wherein pressure, temperature, and composition of formation fluids can continuously fluctuate or

10 change. The distance between the surface-located chemical injection unit and the subsea environment introduces friction losses and a lag between the sensing of a given condition and the execution of measures for addressing that condition. Thus, for instance, a conventionally located chemical injection unit may inject chemicals to remedy a condition that has since changed.

15 The present invention addresses the above-noted problems and provides an enhanced additive injection system suitable for subsea applications.

SUMMARY OF THE INVENTION

This invention provides a system and method for deployment of chemicals or additives in subsea oilwell operations. The chemicals used prevent or reduce build up of harmful elements, such as paraffin or scale and prevent or reduce corrosion of hardware in the wellbore and at the seabed, including pipes and also promote separation and/or processing of formation fluids produced by subsea wellbores. In one aspect, the system includes one or more subsea mounted tanks for storing chemicals, one or more subsea pumping systems for injecting or pumping chemicals into one or more wellbores and/or subsea processing units(s), a system for supplying chemicals to the subsea tanks, which may be via an umbilical interfacing the subsea tanks to a surface chemical supply unit or a remotely-controlled unit or vehicle that can either replace the empty subsea tanks with chemical filled tanks or fill the subsea tanks with the chemicals. The subsea tanks may also be replaced by any other conventional methods. The surface and subsea tanks may include multiple compartments or separate tanks to hold different chemicals which can be deployed into wellbores at different or same time. The subsea chemical injection unit can be sealed in a water-tight enclosure. The subsea chemical storage and injection system decreases the viscosity problems related to pumping chemicals from the surface through umbilical capillary tubings to a subsea installation location that may in some cases be up to 20 miles from the surface pumping station.

The system includes sensors associated with the subsea tank, the subsea pipes carrying the produced fluids, the wellbore, the umbilical and the surface facilities. The surface to subsea interface may use fiber optic cables to monitor the condition of the umbilical and the lines and provide chemical, physical and environmental data, such as chemical composition, pressure, temperature, viscosity etc. Fiber optic sensors along with conventional sensors may also be utilized in the system wellbore. Other suitable sensors to determine the chemical and physical characteristics of the chemical being injected into the wellbore and the fluid extracted from the wellbore may also be used. The sensors may be distributed throughout the system to provide data relating to the properties of the chemicals, the wellbore produced fluid, processed fluid at subsea processing unit and surface unit and the health and operation of the various subsea and surface

equipment.

The surface supply units may include tanks carried by a platform or vessel or buoys associated with the subsea wells. Electric power at the surface may be generated from solar power or from conventional power generators. Hydraulic

5 power units are provided for surface and subsea chemical injection units. Controllers at the surface alone or at subsea locations or in combination control the operation of the subsea injection system in response to one or parameters of interests relating to the system and/or in response to programmed instructions. A two-way telemetry system preferably provides data communication between the

10 subsea system and the surface equipment. Commands from the surface unit are received by the subsea injection unit and the equipment and controllers located in the wellbores. The signals and data are transmitted between and/or among equipment, subsea chemical injection, fluid processing units, and surface equipment. A remote unit, such as at a land facility, may also be provided. The

15 remote location then is made capable of controlling the operation of the chemical injection units of the system of the present invention.

In one embodiment, the present invention provides a subsea additive injection system for treating formation fluids. In one mode, the system injects, monitors and controls the supply of additives into fluids recovered through

20 subsea production wellbores. The system can include a surface facility having a supply unit for supplying additives to a chemical injection unit located at a subsea location.

The chemical injection unit includes a pump and a controller. The pump supplies, under pressure, a selected additive from a chemical supply unit into the

25 subsea wellbore via a suitable supply line. In one embodiment, one or more additives are pumped from an umbilical disposed on the outside of a riser extending to a surface facility. In another embodiment, the additives are supplied from one or more subsea tanks. The controller at a seabed location determines additive flow rate and controls the operation of the pump according to stored

30 parameters in the controller. The subsea controller adjusts the flow rate of the additive to the wellbore to achieve the desired level of chemical additives.

The system of the present invention may be configured for multiple production wells. In one embodiment, such a system includes a separate pump, a fluid line and a subsea controller for each subsea well. Alternatively, a suitable

common subsea controller may be provided to communicate with and to control multiple wellsite pumps via addressable signaling. A separate flow meter for each pump provides signals representative of the flow rate for its associated pump to the onsite common controller. The seabed controller at least 5 periodically polls each flow meter and performs the above-described functions. If a common additive is used for a number of wells, a single additive source may be used. A single or common pump may also be used with a separate control valve in each supply line that is controlled by the controller to adjust their respective flow rates. The additive injection of the present invention may also utilize a 10 mixer wherein different additives are mixed or combined at the wellsite and the combined mixture is injected by a common pump and metered by a common meter. The seabed controller controls the amounts of the various additives into 15 the mixer.

The additive injection system may further include a plurality of sensors 20 downhole which provide signals representative of one or more parameters of interest. Parameter of interest can include the status, operation and condition of equipment (e.g., valves) and the characteristics of the produced fluid, such as the presence or formation of sulfites, hydrogen sulfide, paraffin, emulsion, scale, asphaltenes, hydrates, fluid flow rates from various perforated zones, flow rates 25 through downhole valves, downhole pressures and any other desired parameter. The system may also include sensors or testers that provide information about the characteristics of the produced fluid. The measurements relating to these various parameters are provided to the wellsite controller which interacts with one or more models or programs provided to the controller or determines the 30 amount of the various additives to be injected into the wellbore and/or into a subsea fluid treatment unit and then causes the system to inject the correct amounts of such additives. In one aspect, the system continuously or periodically updates the models based on the various operating conditions and then controls the additive injection in response to the updated models. This provides a closed-loop system wherein static or dynamic models may be utilized to monitor and control the additive injection process. The additives injected using the present invention are injected in very small amounts. Preferably, the flow rate for an additive injected using the present invention is at a rate such that the additive is present at a concentration of from about 1 parts per million (ppm) to

about 10,000 ppm in the fluid being treated.

The surface facility supports subsea chemical injection and monitoring activities. In one embodiment, the surface facility is an offshore rig that provides power and has a chemical supply that provides additives to one or more injection units. This embodiment includes an offshore platform having a chemical supply unit, a production fluid processing unit, and a power supply. Disposed outside of the riser are a power transmission line and umbilical bundle, which transfer electrical power and additives, respectively, from the surface facility to the subsea chemical injection unit. The umbilical bundle can include metal conductors, fiber optic wires, and hydraulic lines.

In another embodiment, the surface facility includes a relatively stationary buoy and a mobile service vessel. The buoy provides access to an umbilical adapted to convey chemicals to the subsea chemical injection unit. In one embodiment, the buoy includes a hull, a port assembly, a power unit, a transceiver, and one or more processors. The umbilical includes an outer protective riser, tubing adapted to convey additives, power lines, and data transmission lines having metal conductors and/or fiber optic wires. The power lines transmit energy from the power unit to the chemical injection unit and/or other subsea equipment. In certain embodiments, the transceiver and processors cooperate to monitor subsea operating conditions via the data transmission lines. Sensors may be positioned in the chemical supply unit, the production fluid processing unit, and the riser. The signals provided by these sensors can be used to optimize operation of the chemical injection unit. The service vessel includes a surface chemical supply unit and a docking station or other suitable equipment for engaging the buoy and/or the port. During deployment, the service vessel visits one or more buoys, and, pumps one or more chemicals to the chemical injection unit via the port and umbilical.

Examples of the more important features of the invention have been summarized rather broadly in order that the detailed description thereof that follows may be better understood and in order that the contributions they represent to the art may be appreciated. There are, of course, additional features of the invention that will be described hereinafter and which will form the subject of the claims appended hereto.

BRIEF DESCRIPTION OF THE DRAWINGS

For a detailed understanding of the present invention, reference should be made to the following detailed description of the one mode embodiments, taken in conjunction with the accompanying drawings, in which like elements have
5 been given like numerals, wherein:

Figure 1 is a schematic illustration of an offshore production facility having an additive injection and monitoring system made according to one embodiment of the present invention;

10 **Figure 2** is a schematic illustration of a additive injection and monitoring system according to one embodiment of the present invention;

Figure 3 shows a functional diagram depicting one embodiment of the system for controlling and monitoring the injection of additives into multiple wellbores, utilizing a central controller on an addressable control bus;

15 **Figure 4** is a schematic illustration of a wellsite additive injection system which responds to in-situ measurements of downhole and surface parameters of interests according to one embodiment of the present invention;

Figure 5A is a schematic illustration of a surface facility having a platform according to one embodiment of the present invention; and

20 **Figure 5B** is a schematic illustration of a surface facility having a service vessel and buoy made according to one embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

25 Referring initially to **Figure 1**, there is schematically shown a chemical injection and monitoring system **100** (hereafter “system **100**”) made in accordance with the present invention. The system **100** may be deployed in conjunction with a surface facility **110** located at a water’s surface **112** that services one or more subsea production wells **60** residing in a seabed **116**.
30 Conventionally, each well **60** includes a well head **114** and related equipment positioned over a wellbore **118** formed in a subterranean formation **120**. The well bores **118** can have one or more production zones **122** for draining hydrocarbons from the formation **120** (“produced fluids” or “production fluid”). The production fluid is conveyed to a surface collection facility (e.g., surface facility **110** or
35 separate structure) or a subsea collection and/or processing facility **126** via a line

127. The fluid may be conveyed to the surface facility **110**-via a line **128** in an untreated state or, preferably, after being processed, at least partially, by the production fluid-processing unit **126**.

The system **100** includes a surface chemical supply unit **130** at the 5 surface facility **110**, a single or multiple umbilicals **140** disposed inside or outside of the riser **124**, one or more sensors **S**, a subsea chemical injection unit **150** located at a remote subsea location (e.g., at or near the seabed **116**), and a controller **152**. The sensors **S** are shown collectively and at representative locations; i.e., water surface, wellhead, and wellbore. In some embodiments, the 10 system **100** can include a power supply **153** and a fluid-processing unit **154** positioned on the surface facility **110**. The umbilical **140** can include hydraulic lines **140h** for supplying pressurized hydraulic fluid, one or more tubes for supplying additives **140c**, and power/data transmission lines **140b** and **140d** such as metal conductors or fiber optic wires for exchanging data and control 15 signals. The chemical injection unit can be sealed in a water-tight enclosure.

During production operations, in one embodiment the surface chemical supply unit **130** supplies (or pumps) one or more additives to the chemical injection unit **150**. The surface chemical supply unit **130** may include multiple tanks for storing different chemicals and one or more pumps to pump chemicals 20 to the subsea tank **131**. This supply of additives may be continuous. Multiple subsea tanks may be used to store a pre-determined amount of each chemical. These tanks **131** then are replenished as needed by the surface supply unit **130**. The chemical injection unit **150** selectively injects these additives into the production fluid at one or more pre-determined locations. In a one mode of 25 operation, the controller **152** receives signals from the sensors **S** regarding a parameter of interest which may relate to a characteristic of the produced fluid. The parameters of interest can relate, for example, to environmental conditions or the health of equipment. Representative parameters include but are not limited to temperature, pressure, flow rate, a measure of one or more of hydrate, 30 asphaltene, corrosion, chemical composition, wax or emulsion, amount of water, and viscosity. Based on the data provided by the sensors **S**, the controller **152** determines the appropriate amount of one or more additives needed to maintain a desired or pre-determined flow rate or other operational criteria and alters the operation of the chemical injection unit **150** accordingly. A surface controller

152S may be used to provide signals to the subsea controller **152** to control the delivery of additives to the wellbore **118** and/or the processing unit **126**.

Referring now to **Figure 2**, there shown a schematic diagram of a subsea chemical injection system **150** according to one embodiment of the present invention. The system **150** is adapted to inject additives **13a** into the wellbore **118** and/or into a subsea surface treatment or processing unit **126**. The system **150** is further adapted to monitor pre-determined conditions (discussed later) and alter the injection process accordingly. The wellbore **118** is shown as a production well using typical completion equipment. The wellbore **118** has a production zone **122** that includes multiple perforations **54** through the formation **120**. Formation fluid **56** enters a production tubing **59** in the well **118** via perforations **54** and passages **62**. A screen **58** in the annulus **51** between the production tubing **59** and the formation **120** prevents the flow of solids into the production tubing **59** and also reduces the velocity of the formation fluid entering into the production tubing **59** to acceptable levels. An upper packer **64a** above the perforations **54** and a lower packer **64b** in the annulus **51** respectively isolate the production zone **122** from the annulus **51a** above and annulus **51b** below the production zone **122**. A flow control valve **66** in the production tubing **59** can be used to control the fluid flow to the seabed surface **116**. A flow control valve **67** may be placed in the production tubing **62** below the perforations **54** to control fluid flow from any production zone below the production zone **122**.

A smaller diameter tubing **68**, may be used to carry the fluid from the production zones to the subsea wellhead **114**. The production well **118** usually includes a casing **40** near the seabed surface **116**. The wellhead **114** includes equipment such as a blowout preventor stack **44** and passages **14** for supplying fluids into the wellbore **118**. Valves (not shown) are provided to control fluid flow to the seabed surface **116**. Wellhead equipment and production well equipment, such as shown in the production well **118**, are well known and thus are not described in greater detail.

Referring still to **Figure 2**, in one aspect of the present invention, the desired additive **13a** is injected into the wellbore **118** via an injection line **14** by a suitable pump, such as a positive displacement pump **18** ("additive pump"). In one aspect, the additive **13a** flows through the line **14** and discharges into the production tubing **60** near the production zone **122** via inlets or passages **15**.

The same or different injection lines may be used to supply additives to different production zones. In **Figure 2**, line **14** is shown extending to a production zone below the zone **122**. Separate injection lines allow injection of different additives at different well depths. The additives **13a** may be supplied from a tank **131** that

5 is periodically filled via the supply line **140**. Alternatively, the additives **13a** may be supplied directly from the surface chemical supply **130** via supply line **140c**. The tank **131** may include multiple compartments and may be replaceable tanks which is periodically replaced. A level sensor **S_L** can provide to the controller **152** or **152S** (Fig. 1) indication of the additive remaining in the tank **131**. When the

10 additive level falls below a predetermined level, the tank is replenished or replaced. Alternatively a remotely operated vehicle **700** ("ROV") may be used to replenish the tank via feed line **140**. The ROV **700** attaches to the supply line and replenishes the tank **131**. Other conventional methods may be used to replace tank **131**. Replaceable tanks are preferably quick disconnect types (e.g.,

15 mechanical, hydraulic, etc.). Of course, certain embodiments can include a combination of supply arrangements.

In one embodiment, a suitable high-precision, low-flow, flow meter **20** (such as gear-type meter or a nutating meter) measures the flow rate through line **14** and provides signals representative of the flow rate. The pump **18** is

20 operated by a suitable device **22** such as a motor. The stroke of the pump **18** defines fluid volume output per stroke. The pump stroke and/or the pump speed are controlled, e.g., by a 4 - 20 milliamperes control signal to control the output of the pump **18**. The control of air supply controls a pneumatic pump. Any suitable pump and monitoring system may be used to inject additives into the wellbore

25 **118**.

In one embodiment of the present invention, a seabed controller **80** controls the operation of the pump **18** by utilizing programs stored in a memory **91** associated with the subsea controller **80**. The subsea controller **80** preferably includes a microprocessor **90**, resident memory **91** which may include read only

30 memories (ROM) for storing programs, tables and models, and random access memories (RAM) for storing data. The microprocessor **90** utilizes signals from the flow meter **20** received via line **21** and programs stored in the memory **91** to determine the flow rate of the additive. The wellsite controller **80** can be programmed to alter the pump speed, pump stroke or air supply to deliver the

desired amount of the additive **13a**. The pump speed or stroke, as the case may be, is increased if the measured amount of the additive injected is less than the desired amount and decreased if the injected amount is greater than the desired amount.

5 The seabed controller **80** preferably includes protocols so that the flow meter **20**, pump control device **22**, and data links **85** made by different manufacturers can be utilized in the system **150**. In the oil industry, the analog output for pump control is typically configured for 0-5 VDC or 4-20 milliamperes (mA) signal. In one mode, the subsea controller **80** can be programmed to
10 operate for such output. This allows for the system **150** to be used with existing pump controllers. A power unit **89** provides power to the controller **80**, converter **83** and other electrical circuit elements. The power unit **89** can include an AC power unit, an onsite generator, and/or an electrical battery that is periodically charged from energy supplied from a surface location. Alternatively, power may
15 be supplied from the surface via a power line disposed along the riser **124** (discussed in detail below).

Still referring to **Figure 2**, the produced fluid **69** received at the seabed surface **116** may be processed by a treatment unit or processing unit **126**. The seabed processing unit **126** may be of the type that processes the fluid **69** to
20 remove solids and certain other materials such as hydrogen sulfide, or that processes the fluid **69** to produce semi-refined to refined products. In such systems, it is desired to periodically or continuously inject certain additives. Thus, the system **150** shown in **Figure 1** can be used for injecting and monitoring additives **13b** into the processing unit **126**. These additives may be the same or
25 different from the additives injected into the wellbore **118**. These additives **13b** are suitable to process the produced wellbore fluid before transporting it to the surface. In configuration of **Fig. 2**, the same chemical injection unit may be utilized to pump chemicals in multiple wellbores, subsea pipelines and/or subsea processing units.

30 In addition to the flow rate signals **21** from the flow meter **20**, the seabed controller **80** may be configured to receive signals representative of other parameters, such as the rpm of the pump **18**, or the motor **22** or the modulating frequency of a solenoid valve. In one mode of operation, the wellsite controller **80** periodically polls the meter **20** and automatically adjusts the pump controller

22 via an analog input 22a or alternatively via a digital signal of a solenoid controlled system (pneumatic pumps). The controller 80 also can be programmed to determine whether the pump output, as measured by the meter 20, corresponds to the level of signal 22a. This information can be used to

5 determine the pump efficiency. It can also be an indication of a leak or another abnormality relating to the pump 18. Other sensors 94, such as vibration sensors, temperature sensors may be used to determine the physical condition of the pump 18. Sensors S that determine properties of the wellbore fluid can provide information of the treatment effectiveness of the additive being injected.

10 Representative sensors include, but are not limited to, a temperature sensor, a viscosity sensor, a fluid flow rate sensor, a pressure sensor, a sensor to determine chemical composition of the production fluid, a water cut sensor, an optical sensor, and a sensor to determine a measure of at least one of asphaltene, wax, hydrate, emulsion, foam or corrosion. The information provided

15 by these sensors can then be used to adjust the additive flow rate as more fully described below in reference to **Figure 3** and **4**.

It should be understood that a relatively small amount of additives are injected into the production fluid during operation. Accordingly, rather considerations such as precision in dispensing additives can be more relevant

20 than mere volumetric capacity. Preferably, the flow rate for an additive injected using the present invention is at a rate such that the additive is present at a concentration of from about 1 parts per million (ppm) to about 10,000 ppm in the fluid being treated. More preferably, the flow rate for an additive injected using the present invention is at a rate such that the additive is present at a

25 concentration of from about 1 ppm to about 500 ppm in the fluid being treated. Most preferably the flow rate for an additive injected using the present invention is at a rate such that the additive is present at a concentration of from about 10 ppm to about 400 ppm in the fluid being treated.

As noted above, it is common to drill several wellbores from the

30 same location. For example, it is common to drill 10-20 wellbores from a single offshore platform. After the wells are completed and producing, a separate subsea pump and meter are installed to inject additives into each such wellbore.

Figure 3 shows a functional diagram depicting a system 200 for controlling and monitoring the injection of additives into multiple wellbores 202a-

202m according to one embodiment of the present invention. In the system configuration of **Figure 3**, a separate pump supplies an additive via supply lines **140** from a surface chemical supply **130** (Fig. 1) to each of the wellbores **202a-202m**. For example, pump **204a** supplies an additive and the meter **208a**

5 measures the flow rate of the additive into the wellbore **202a** and provides corresponding signals to a central wellsite controller **240**. The wellsite controller **240** in response to the flow meter signals and the programmed instructions controls the operation of pump control device or pump controller **210a** via a bus **241** using addressable signaling for the pump controller **210a**. Alternatively, the

10 wellsite controller **240** may be connected to the pump controllers via a separate line. The wellsite controller **240** also receives signal from sensor **S1a** associated with pump **204a** via line **212a** and from sensor **S2a** associated with the pump controller **210a** via line **212a**. Such sensors may include rpm sensor, vibration sensor or any other sensor that provides information about a parameter of

15 interest of such devices. Additives to the wells **202b-202m** are respectively supplied by pumps **204b-204m** from sources **206b-206m**. Pump controllers **210b-210m** respectively control pumps **204b-204m** while flow meters **208b-208m** respectively measure flow rates to the wells **202b-202m**. Lines **212b-212m** and lines **214b-214m** respectively communicate signals from sensor **S1b-S1m** and **S2b-S2m** to the central controller **240**. The controller **240** utilizes memory **246** for storing data in memory **244** for storing programs in the manner described above in reference to system **100** of **Figure 1**. The individual controllers communicate with the sensors, pump controllers and remote controller via suitable corresponding connections.

25 The central wellsite controller **240** controls each pump independently. The controller **240** can be programmed to determine or evaluate the condition of each of the pumps **204a-204m** from the sensor signals **S1a-S1m** and **S2a-S2m**. For example the controller **240** can be programmed to determine the vibration and rpm for each pump. This can provide information about the effectiveness of each

30 such pump.

Figure 4 is a schematic illustration of a closed-loop additive injection system **300** which responds to measurements of downhole and surface parameters of interest according to one embodiment of the present invention. Certain elements of the system **300** are common with the system **150** of **Figure 1**.

2. For convenience, such common elements have been designated in **Figure 4** with the same numerals as specified in **Figure 2**.

The well **118** in **Figure 4** further includes a number of downhole sensors **S_{3a}-S_{3m}** for providing measurements relating to various downhole parameters.

5 The sensors may be located at wellhead over the at least one wellbore, in the wellbore, and/or in a supply line between the wellhead and the subsea chemical injection unit. Sensor **S_{3a}** provide a measure of chemical and physical characteristics of the downhole fluid, which may include a measure of the paraffins, hydrates, sulfides, scale, asphaltenes, emulsion, etc. Other sensors
10 and devices **S_{3m}** may be provided to determine the fluid flow rate through perforations **54** or through one or more devices in the well **118**. These sensors may be distributed along the wellbore and may include fiber optic and other sensors. The signals from the sensors may be partially or fully processed downhole or may be sent uphole via signal/date lines **302** to a wellsite controller
15 **340**. In the configuration of **Figure 3**, a common central control unit **340** is preferably utilized. The control unit is a microprocessor-based unit and includes necessary memory devices for storing programs and data.

The system **300** may include a mixer **310** for mixing or combining at the wellsite a plurality of **additive #1 - additive #m** stored in sources **313a-312m** respectively. The sources **313a-312m** are supplied with additives via supply line **140**. In some situations, it is desirable to transport certain additives in their component forms and mix them at the wellsite for safety and environmental reasons. For example, the final or combined additives may be toxic, although while the component parts may be non-toxic. Additives may be shipped in
25 concentrated form and combined with diluents at the wellsite prior to injection into the well **118**. In one embodiment of the present invention, additives to be combined, such as additives **additive #1-additive #m** are metered into the mixer by associated pumps **314a-314m**. Meters **316a-316m** measure the amounts of the additives from sources **312a-312m** and provide corresponding signals to the
30 control unit **340**, which controls the pumps **314a-314m** to accurately dispense the desired amounts into the mixer **310**. A pump **318** pumps the combined additives from the mixer **310** into the wellbore **118**, while the meter **320** measures the amount of the dispensed additive and provides the measurement signals to the controller **340**. A second additive required to be injected into the well **118** may be

stored in the source tank 131, from which source a pump 324 pumps the required amount of the additive into the well. A meter 326 provides the actual amount of the additive dispensed from the source tank 131 to the controller 340, which in turn controls the pump 324 to dispense the correct amount.

5 The wellbore fluid reaching the surface may be tested on site with a testing unit 330. The testing unit 330 provides measurements respecting the characteristics of the retrieved fluid to the central controller 340. The central controller utilizing information from the downhole sensors S_{3a}-S_{3m}, the tester unit data and data from any other surface sensor (as described in reference to Figure
10 2) computes the effectiveness of the additives being supplied to the well 118 and determine therefrom the correct amounts of the additives and then alters the amounts, if necessary, of the additives to the required levels. The controller 340 may also receive commands from the surface controller 152s and/or a remote controller 152s to control and/or monitor the wells 202a-202m

15 Thus, the system of the present invention at least periodically monitors the actual amounts of the various additives being dispensed, determines the effectiveness of the dispensed additives, at least with respect to maintaining certain parameters of interest within their respective predetermined ranges, determines the health of the downhole equipment, such as the flow rates and
20 corrosion, determines the amounts of the additives that would improve the effectiveness of the system and then causes the system to dispense additives according to newly computed amounts. The models 344 may be dynamic models in that they are updated based on the sensor inputs.

25 The system of the present invention can automatically take broad range of actions to assure proper flow of hydrocarbons through pipelines, which not only can minimize the formation of hydrates but also the formation of other harmful elements such as asphaltenes. Since the system 300 is closed loop in nature and responds to the in-situ measurements of the characteristics of the treated fluid and the equipment in the fluid flow path, it can administer the optimum
30 amounts of the various additives to the wellbore or pipeline to maintain the various parameters of interest within their respective limits or ranges.

Referring now to Figure 5A, there is shown one embodiment of a surface facility and a remote control station for supporting and controlling the subsea chemical injection and monitoring activities of a subsea chemical injection

system, such as system 150 of **Figure 1**. The **Figure 5A** surface facility 500 can provide power and additives as needed to one or more subsea chemical injection units 150 (**Fig. 1**). Also, the surface facility 500 includes equipment for processing, testing and storing produced fluids. A one mode surface facility 500

5 includes an offshore platform or rig or a vessel 510 having a chemical supply unit 520, a production fluid processing unit 530, a power supply 540, a controller 532 and may include a remote controller 533 via a satellite or other long distance means. The chemical supply unit 520 may include separate tanks for each type of chemical desired to be supplied therefrom to the chemical injection unit 150

10 (**Fig. 1**) via a supply line or umbilical bundle 522 that is disposed inside or outside of a riser 550. Each chemical/additive can either have a dedicated supply line (*i.e.*, multiple lines) or share one or more supply lines. Likewise, the umbilical bundle 522 can include power and/or data transmission lines 544 for transmitting power from the power supply 540 to the subsea components of the

15 system 100 and transmitting data and control signals between the surface controller 532 and the subsea controller 152 (**Fig. 1**). Suitable lines 544 include fiber optic wires and metal conductors adapted to convey data, electrical signals and power. The processing unit 530 receives produced fluid from the well head 114 (**Fig. 1**) via the riser 550. Sensors S₄ may be positioned in the chemical

20 supply unit 520, the production fluid processing unit 530, and the riser 550 (sensors S_{4a-c}, respectively). Sensors S_{4c} may be distributed along the riser and/or umbilical to provide signals representative of fluid flow, physical and chemical characteristics of the additives and production fluid and environmental conditions. As explained earlier, measurement provided by these sensors can be

25 used to optimize operation of the chemical injection unit 150 (**Fig. 1**). It will be appreciated that a single surface facility as shown in **Figure 5A** may be used to service multiple subsea oilfields.

Referring now to **Figure 5B**, there is shown another embodiment of a surface facility. The **Figure 5B** surface facility 600 supplies additives on-demand or on a pre-determined basis to the chemical injection unit 150 (**Fig. 1**) without using a dedicated chemical supply unit. A one mode surface facility 600 includes a buoy 610 and a service vessel 630.

The buoy 610 provides a relatively stationary access to an umbilical 611 and a riser 612 adapted to convey power, data, control signals, and chemicals to

the chemical injection unit 150 (**Fig. 1**). The buoy 610 includes a hull 614, a port assembly 616, a power unit 618, a transceiver 620, and one or more processors 624. The hull 614 is of a conventional design and can be fixed, floating, semi-submersed, or full submersed. In certain embodiments, the hull 614 can include
5 known components such as ballast tanks that provide for selective buoyancy. The port 616 is suitably disposed on the hull 614 and is in fluid communication with the conduit 612. The conduit 612 includes an outer protective riser 612a and the umbilical 611, which can include single or multiple tubing 612b adapted to convey chemicals and additives, power lines 612c, and data transmission lines
10 612d. The power lines 612d transmit stored or generated power of the power unit 618 to the chemical injection unit (**Fig. 1**) and/or other subsea equipment. The power lines 612d can also include hydraulic lines for conveying hydraulic fluid to subsea equipment. Power may be generated by a conventional generator 622 and/or stored in batteries 621 which can be charged via a solar
15 power generation system 619. The transceiver 620 and processors 624 cooperate to monitor subsea operating conditions via the data transmission lines 612d. The data transmission lines can use metal conductors or fiber optic wires. In certain embodiments, the transceiver 620 and processors 624 can determine whether any subsea equipment is malfunctioning or whether the chemical
20 injection unit 130 (**Fig. 1**) will exhaust its supply of one or more additives. Upon making such a determination, the transceiver 620 can be used to transmit this determination to a control facility (not shown). Sensors S₅ may be positioned in the production fluid processing unit 640 (sensor S_{5a}), the riser 612 (sensor S_{5b}), or other suitable location. As explained earlier, measurement provided by these
25 sensors can be used to optimize operation of the chemical injection unit 130 (**Fig. 1**). The subsea chemical injection unit can be sealed in a water-tight enclosure.

The service vessel 630 includes a surface chemical supply unit 632 and a suitable equipment (not shown) for engaging the buoy 610 and/or the port 616. The service vessel 630 may be self-powered (*e.g.*, a ship or a towed structure).
30 During deployment, the service vessel 630 visits one or more buoys 610 on a determined schedule or on an as-needed basis. Upon making up a connection to the port 616, one or more chemicals is pumped down to the chemical storage tank 130 (**Fig. 1**) via the tubing 612b. After the pumping operation is complete, the buoy 610 is released and the service vessel 630 is free to visit other buoys

610. It should be appreciated that the buoy 630 according to the present invention are less expensive than conventional offshore platforms.

Produced fluid from the well head 114 (**Fig. 1**) is conveyed via a line 632 to a fluid processing unit 640. The processed produced fluids are then 5 transferred to a surface or subsea collection facility via line 642.

Referring to **Figure 1, 5A and 5B**, the system may further include devices that heat production fluid in subsea lines, such as line 127. The power for heating devices (189) can be tapped from power supplied by the surface unit to the subsea chemical injection unit 150 or to any other subsea device, such as 10 wellhead valves. The sensors S monitor the condition of the production fluid. The system of **Figures 1-5** controls and monitors the injection of chemicals into subsea wellbores 118. A subsea chemical injection alone can control and monitor the injection of chemicals into wellbores 118 and underwater processing facility 126. The system can also monitor the fluid carry lines 127. The unit 150 15 can control and monitor the chemical injection in response to various sensor measurements or according to programmed instructions. The chemical sensor in the system provides information from various places along the wellbore 118, pipe 127, fluid processing unit 126, and riser 124 or 150. The other sensors provide information about the physical or environmental conditions. The subsea controller 152, the surface controller 152s and the remote controller 152s 20 cooperate with each other and in response to one or more sensor measurements in parameters of interest control and/or monitor the operation of the entire system shown in **Figs. 1-5**.

While the foregoing disclosure is directed to the one mode embodiments 25 of the invention, various modifications will be apparent to those skilled in the art. It is intended that all variations within the scope and spirit of the appended claims be embraced by the foregoing disclosure.